



## Original Research Article

# A computer method for biomechanical analysis of the balance of acrobatic figures performed by two gymnasts

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### Abstract:

In this paper, we present a biomechanical analysis of the balance of an acrobatic figure constructed by two girls. For the analysis, the Kinovea computer software was used. We demonstrate that the balance in the sagittal plane depends on the size of the base gymnast's feet and the angle between her feet: increasing the size of the feet of the base gymnast improves the balance, while increasing the angle between her feet weakens the balance. Balance also depends on the heights and masses of gymnasts: increasing the gymnasts' heights and/or the top gymnast's mass weakens the balance, while increasing the base gymnast's mass improves it. Such analysis is especially important when acrobats are relatively young (10-15 years old), as their bodies are undergoing growth and body parameters (such as sizes and weights of body parts) change non-proportionally.

**Keywords:** acrobatic gymnastics, sports biomechanics, balance, equilibrium.

**Introduction.** In many sports, the quality of performance depends on the athletes' ability to maintain balance. In some sports such as acrobatics, gymnastics, weight lifting and surfing, this ability plays a decisive role. To assess the balance of acrobatic figures, researchers use force plates and calculate deviations of the center of pressure from the average value [1, 2].

Scientists also use video-computer analysis, where the coordinates of athletes' centers of gravity may be calculated from video recordings [3-8].

At the same time, we know that the result in many sports also depends on the physical parameters of athletes such as their heights, masses, etc [9, 10]. In this paper, we study

how the balance of the hand-to-hand stand in Fig. 1 depends on the heights, masses and other physical parameters of the athletes.

**Research methods.** From the photo, using line calibration and the human model tool available in the Kinovea computer program, we can find the coordinates of the centers of mass for each gymnast and then calculate the coordinates of the total center of mass of the whole acrobatic figure  $CM(X_{CM}, Y_{CM})$ .  $CM_1(78.86 \text{ cm}, 92.89 \text{ cm})$  and  $CM_2(83.65 \text{ cm}, 258.02 \text{ cm})$  – are the centers of mass of the base and top gymnasts, respectively, while  $CM(80.60 \text{ cm}, 152.94 \text{ cm})$  is the total center of mass of the whole acrobatic figure, which may be obtained using standard formulas:  $X_{CM} = (m_1/(m_1+m_2)) \cdot X_{CM_1} + (m_2/(m_1+m_2)) \cdot X_{CM_2}$

and  $Y_{CM} = (m_1/(m_1+m_2)) \cdot Y_{CM}' + (m_2/(m_1+m_2)) \cdot Y_{CM}''$ , where  $m_1=42$  kg is the mass of the base gymnast,  $m_2=24$  kg is the mass of the top

gymnast,  $h_1=160$  cm and  $h_2=130$  cm are their heights, and  $(X_{CM}', Y_{CM}')$  and  $(X_{CM}'', Y_{CM}'')$  are the coordinates of their centers of mass.

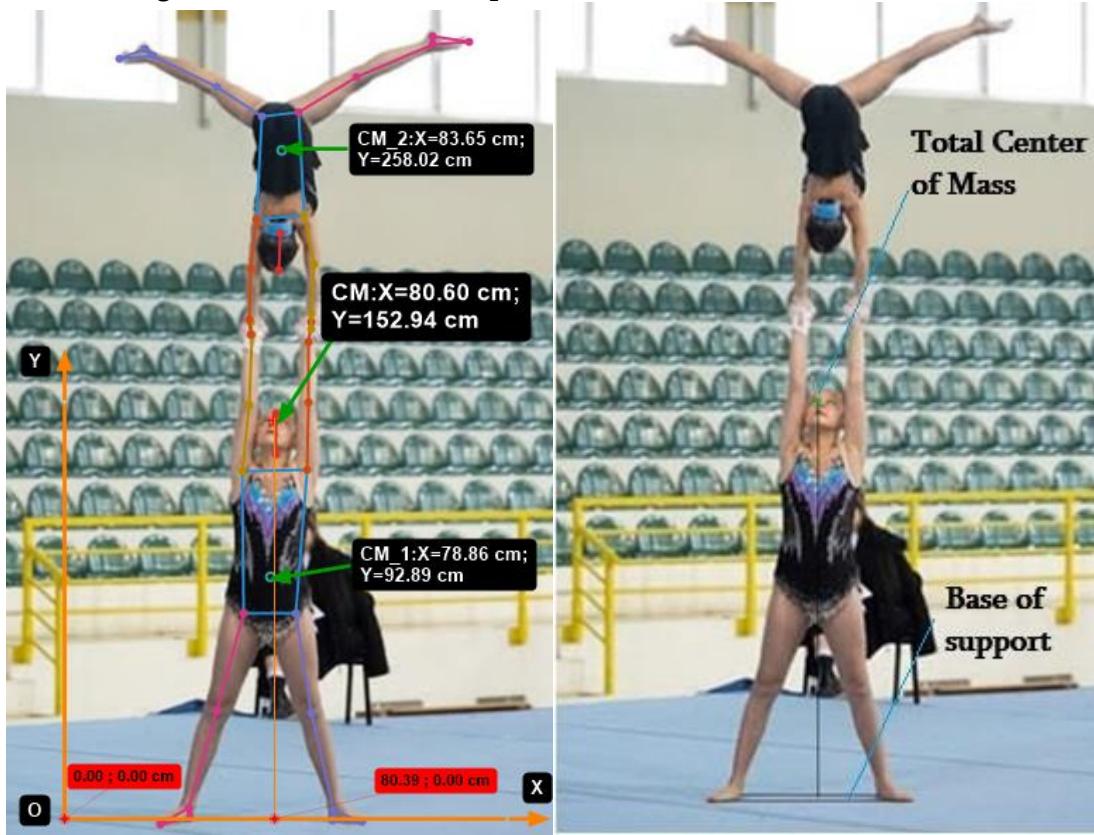


Fig. 1. The figure shows the centers of mass of the gymnasts obtained using Kinovea software and the calculated total center of mass of the whole acrobatic figure.

The balance of the hand-to-hand stand in the frontal plane is achieved by keeping a fairly large distance between the feet of the base gymnast. While balance in the sagittal plane during backward and forward leanings is much more difficult to achieve. As it was shown in our recent publication the balance of the stand in the sagittal plane may be characterized by four angles  $\alpha_{cr}'$ ,  $\alpha_{cr}''$ ,  $\alpha_{opt}=\alpha_{cr}'$  and  $\alpha_{cr}=\alpha_{cr}'+\alpha_{cr}''$  [10].

The first angle  $\alpha_{cr}'$  characterizes the maximum leaning of the body in the backward direction while maintaining balance, the second angle  $\alpha_{cr}''$  characterizes the maximum leaning in the forward direction without losing equilibrium, the

third angle  $\alpha_{opt}$  describes the optimal position of the total center of gravity of the acrobatic stand when it is exactly over the geometric center of the base of support and the fourth angle  $\alpha_{cr}=\alpha_{cr}'+\alpha_{cr}''$  characterizes the overall stability of the acrobatic figure in the sagittal plane during leanings backwards and forwards.

These angles depend on  $Y_{CM} \approx 153$  cm - the vertical coordinate of CM and  $l=|KM|=|LN|=22$  cm - the base gymnast's foot length, and  $\alpha_{feet} \approx 70^\circ$  - the angle between her feet (Fig. 2).

$$\alpha_{cr}' = \arcsin((1/4) \cdot d / Y_{CM})$$

$$\text{and } \alpha_{cr}'' = \arcsin((3/4) \cdot d / Y_{CM}), \quad (1)$$

where  $d=|AB|=l \cdot \cos(\alpha_{feet}/2)$ .

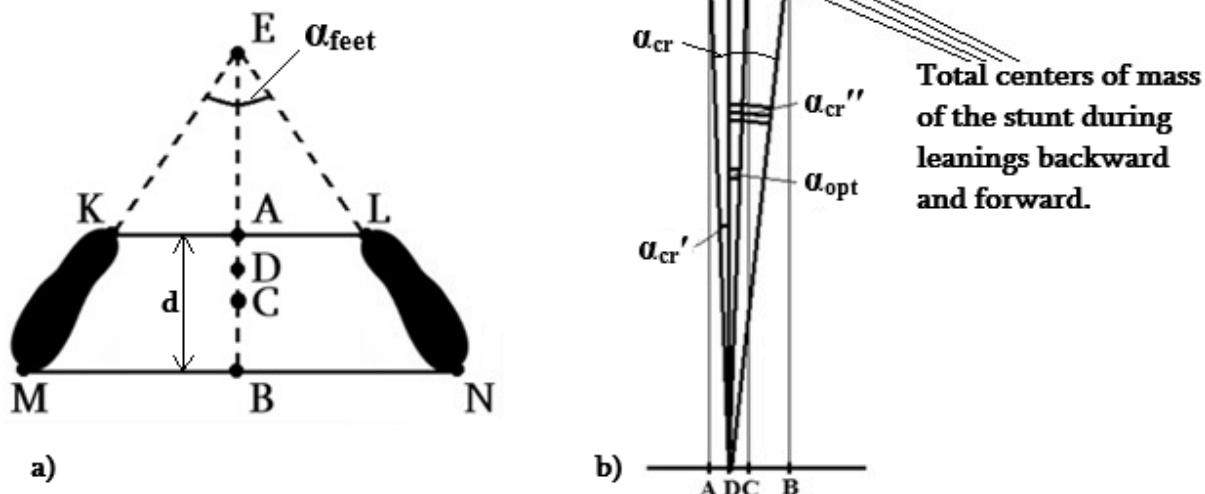


Fig. 2. a.) the feet of the base gymnast; b.) the angles  $\alpha_{cr}'$ ,  $\alpha_{cr}''$ ,  $\alpha_{opt}=\alpha_{cr}'$  and  $\alpha_{cr}$  describing the balance of the acrobatic figure in the sagittal plane.

Using formulas (1), we can calculate values of the critical angles  $\alpha_{cr}'=1.69^\circ$ ,  $\alpha_{cr}''=5.07^\circ$ ,  $\alpha_{opt}=1.69^\circ$  and  $\alpha_{cr}=6.76^\circ$ .

**Discussion of the results of the study.**  
Table 1 demonstrates how variations of the basic physical parameters of the gymnasts  $m_1$ ,  $m_2$ ,  $h_1$ ,  $h_2$ ,  $l$ , and the angle between the feet of the base gymnast  $\alpha_{feet}$  affect the calculated

values of the critical angles  $\alpha_{cr}'$ ,  $\alpha_{cr}''$ ,  $\alpha_{opt}=\alpha_{cr}'$  and  $\alpha_{cr}$ .

Table 1. The table shows how the changes of the physical parameters of the gymnasts affect the balance of the whole acrobatic figure.

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#	Variations of $m_1$ , $m_2$ , $h_1$ , $h_2$ , $l$ and $\alpha_{feet}$						Calculated parameters		
	$\Delta m_1$	$\Delta m_2$	$\Delta h_1$	$\Delta h_2$	$\Delta l$	$\Delta \alpha_{feet}$	$\Delta \alpha_{cr}'$	$\Delta \alpha_{cr}''$	$\Delta \alpha_{cr}$
1	5 kg	0	0	0	0	0	0.05°	0.14°	0.19°
2	0	5 kg	0	0	0	0	-0.08°	-0.23°	-0.31°
3	0	0	10 cm	0	0	0	-0.08°	-0.25°	-0.33°
4	0	0	0	10 cm	0	0	-0.02°	-0.06°	-0.08°
5	0	0	0	0	2 cm	0	0.15°	0.46°	0.62°
6	0	0	0	0	0	10°	-0.11°	-0.33°	-0.44°

From Table 1, we can see that the balance of the whole acrobatic figure is most sensitive to the base gymnast's foot length  $l$  and the angle between her feet  $\alpha_{feet}$ : the increase of the foot length  $l$  by 2 cm improves  $\alpha_{cr}$  by  $0.62^\circ$ , while the increase of the angle  $\alpha_{feet}$  by  $10^\circ$  decreases  $\alpha_{cr}$  by  $0.44^\circ$ .

$\alpha_{cr}$  is also sensitive to the height of the base gymnast and the mass of the top gymnast: the increase of  $h_1$  by 10 cm decreases  $\alpha_{cr}$  by  $0.33^\circ$ , while the increase of  $m_2$  by 5 kg leads to the decrease of  $\alpha_{cr}$  by  $0.31^\circ$ . From Table 1 we see, that  $\alpha_{cr}$  is less sensitive to variations of  $m_1$  and  $h_2$ .

**Conclusions.** In this study, we show that the balance of the hand-to-hand stand depends not only on the professionalism of gymnasts, but also on their physical parameters and is most sensitive to the changes of two parameters: the foot size  $l$  and angle  $\alpha_{feet}$  between the feet of the base gymnast. This fact is very important when working with young gymnasts, who are in the stage of intensive growth and development accompanied by changes in physical parameters. Trainers can use force plates to evaluate the quality of performance, but they should also take into account changes in the physical parameters of athletes.

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### აბსტრაქტი:

ნაშრომში წარმოდგენილია ორი გოგონასაგან აგებული აკრობატული ფიგურის ბალანსის ბიომექანიკური ანალიზი. ანალიზი ჩატარდა კომპიუტერული პროგრამული უზრუნველყოფა Kinovea-ს გამოყენებით. შედეგად, ნაჩვენებია, რომ საგიტალურ სიბრტყეში ბალანსი დამოკიდებულია ქვედა ტანმოვარჯიშის ტერფის ზომაზე და კუთხეზე ტერფებს შორის: ტერფის ზომის გაზრდა ზრდის ბალანსის მდგრადობას, ხოლო ტერფებს შორის კუთხის გაზრდა პირიქით ამცირებს წონასწორობას. ბალანსი ასევე დამოკიდებულია ტანმოვარჯიშების სიმაღლეებზე და მასებზე: ტანმოვარჯიშების სიმაღლეების და ზედა ტანმოვარჯიშის წონის ზრდა ამცირებს ბალანსს, ხოლო ქვედა ტანმოვარჯიშის მასის ზრდა აუმჯობესებს მას. ასეთი ანალიზი განსაკუთრებით მნიშვნელოვანია, როდესაც აკრობატები შედარებით პატარა ასაკის არიან (10-15 წელი), როცა მათი ორგანიზმები განიცდიან ზრდას და სხეულების პარამეტრები (სხეულის ნაწილების ზომები და წონები) არაპროპორციულად იცვლება.

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